

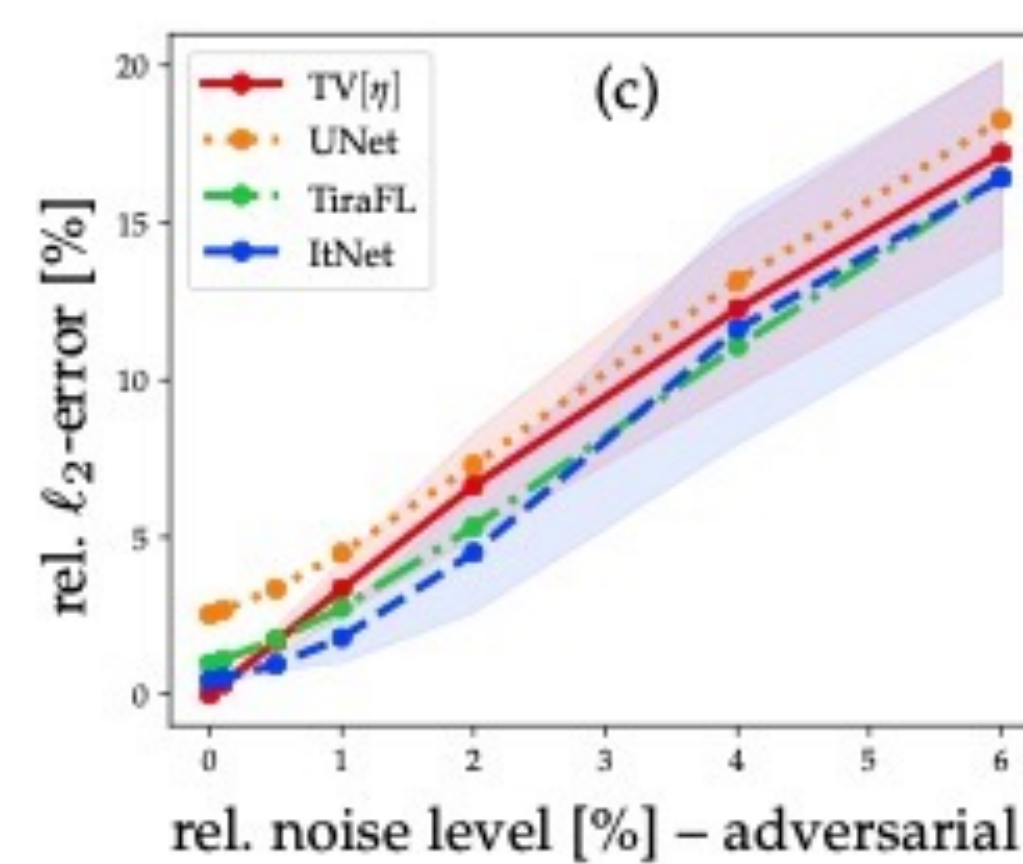
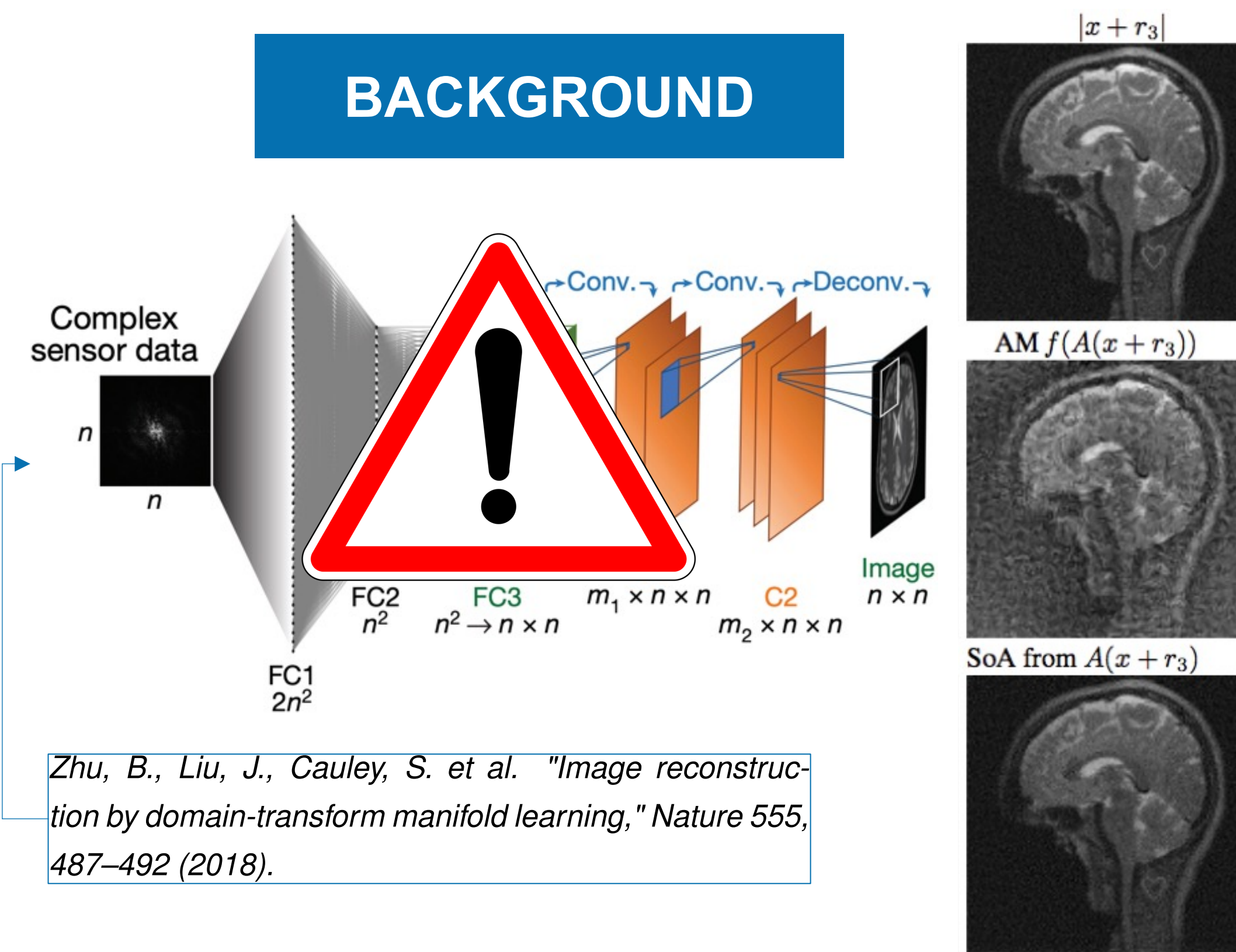
STABILITY OF IMAGE-RECONSTRUCTION ALGORITHMS

Pol del Aguila Pla^{1,2}, Sebastian Neumayer², and Michael Unser²

1: CIBM Center for Biomedical Imaging, SP EPFL Mathematical Imaging, Switzerland

2: Biomedical Imaging Group at the École polytechnique fédérale de Lausanne, Lausanne, Switzerland

BACKGROUND



M. Genzel, J. Macdonald, and M. Marz "Solving inverse problems with deep neural networks - Robustness included," IEEE Transactions on Pattern Analysis and Machine Learning - Early Access (2022)

- Dangerous NN-based image-reconstruction methods (e.g., Zhu 2018).
- Stability problems (e.g., Antun 2020).
- Questioning traditional methods (e.g., Genzel 2022).

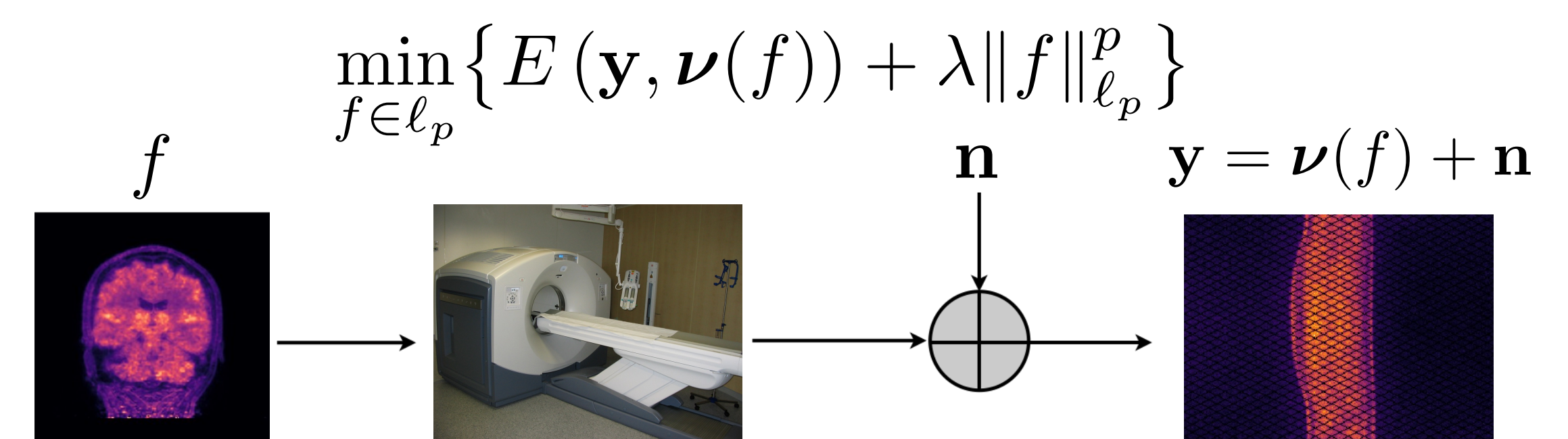
AIMS

- Towards the objective, quantitative comparison of stability in image-reconstruction methods.
- Obtain (computable) bounds of the form:

$$\|f_{y_1} - f_{y_2}\|_{\ell_p} \leq K(Y) \|y_1 - y_2\|_2^\beta,$$

where f_y is the reconstruction for a measurement vector $y \in \mathbb{R}^M$

- Focus on ℓ_p -regularized linear inverse problems



METHODS

- Analysis of sufficient conditions for stability in abstract optimization problems that depend on the measurements and the reconstructed image.
 - Gradient of the data-fidelity term w.r.t. f has to be Lipschitz w.r.t. y
 - Regularizer has to be α -uniform convex
- Analysis of the growth of the gradient of the ℓ_p regularizer.

RESULTS

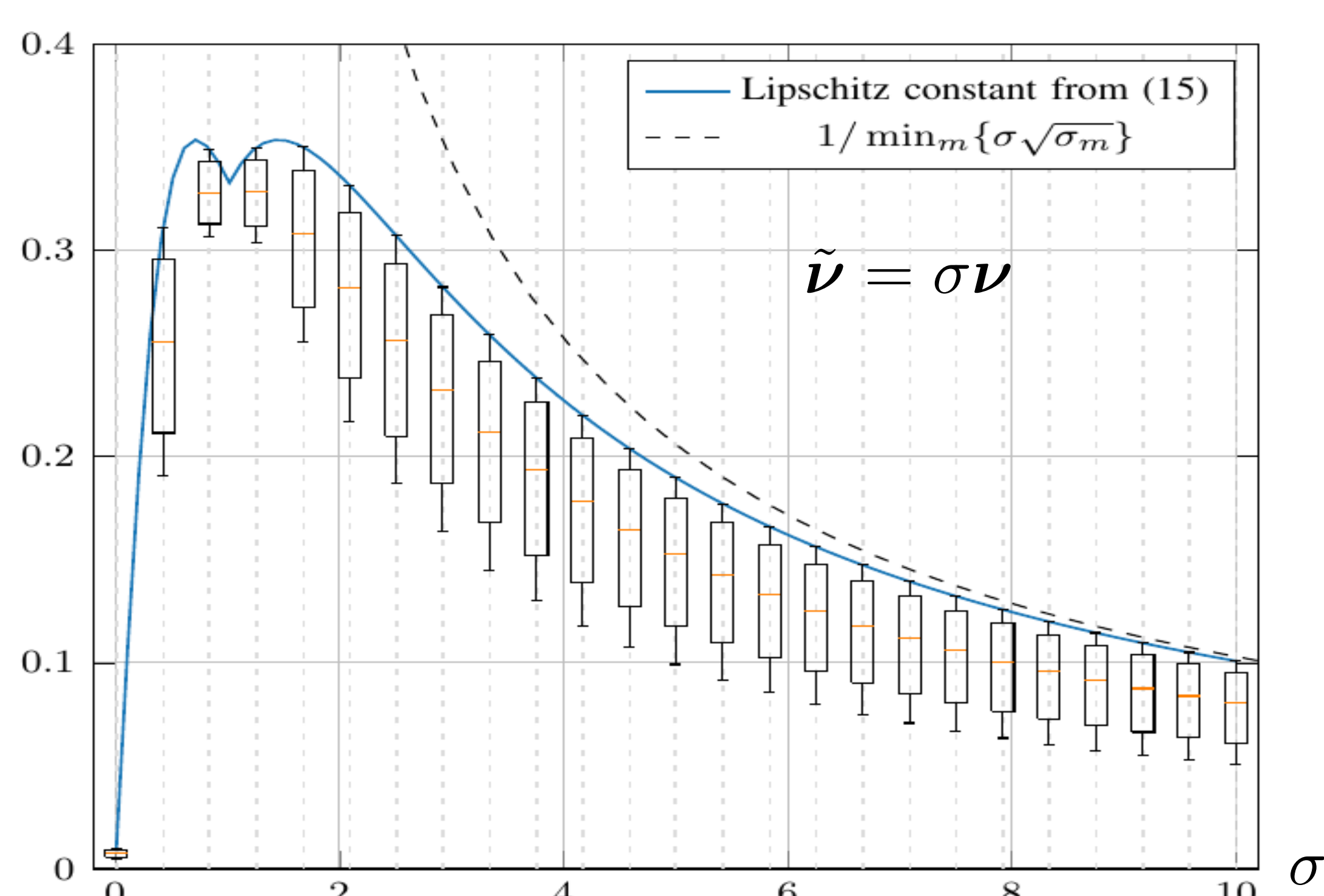


for $p = 2$

- For Tikhonov-regularized least-squares (Lipschitz stability, i.e., $\beta = 1$)

$$\|f_{y_1} - f_{y_2}\|_{\mathcal{H}} \leq \max_{m \in \{1, 2, \dots, M\}} \frac{\sqrt{\sigma_m}}{\sigma_m + 2\lambda} \|y_1 - y_2\|_2$$

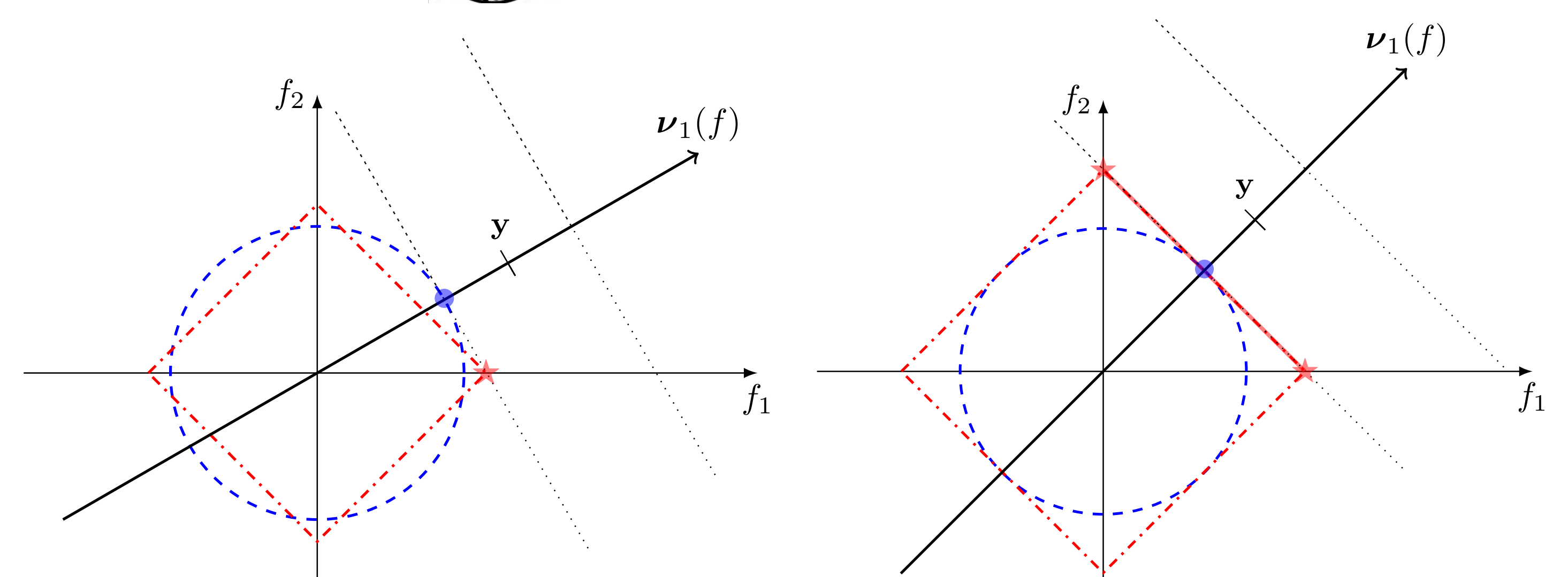
σ_m : eigenvalues of the Gram matrix $\mathbf{H}_{m,n} = \langle \nu_n, \nu_m \rangle$



RESULTS



for $p = 1$



- Unique, sparse solution
- Lipschitz stability, i.e., $\beta = 1$, but unknown K .
- Infinite set of solutions, sparse extremes
- Stability not even defined

RESULTS

for other p

- For $p \in (1, 2)$, local Lipschitz stability

$$\|f_{y_1} - f_{y_2}\|_{L_p} \leq \frac{(2r_p(Y))^{2-p} K_p}{\lambda p(p-1)} \|y_1 - y_2\|_2$$

- For $p \in (2, \infty)$, Hölder stability

$$\|f_{y_1} - f_{y_2}\|_{L_p} \leq \left(\frac{2^{p-2} K_p}{\lambda p} \right)^{\frac{1}{p-1}} \|y_1 - y_2\|_2^{\frac{1}{p-1}}$$

CONCLUSION

- Traditional image-reconstruction methods do provide concrete stability guarantees, if properly used.
- Improved insight into the workings of ℓ_p -regularized linear inverse problems